ELECTRONICS

Motors B	4
Sensors B1	2
Controllers B1	4

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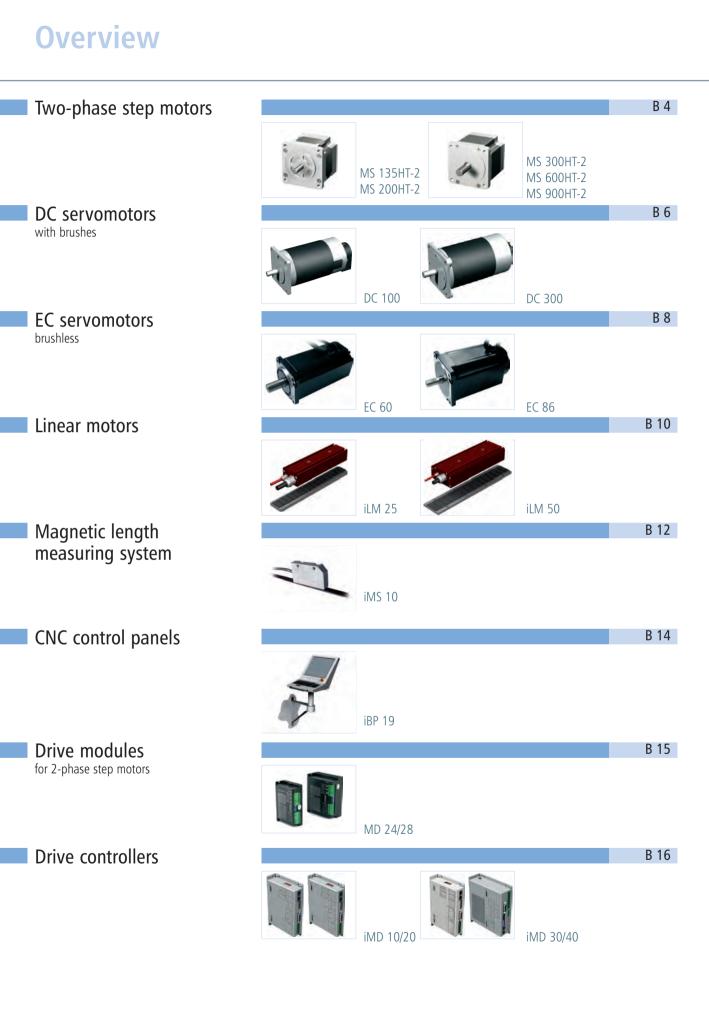
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### **Overview** Motion kits B 18 iMK 20 S/L iMK 40 S/L PC controller B 19 iPC 15 CAN PCI board B 20 iCC 10/20 CAN B 21 controller components CAN I-O modules CPC 12 Step controllers Single axis controller B 23 IT 116 Flash Step controllers B 24 Multiple axis controller iMC-S8 iMC-P Servo controller B 26 Single axis controller MC 1-10 MC 1-20 B 27 Servo controller Multiple axis controller iMC-DC / iMC-EC iPU-DC / iPU-EC **CAN-CNC** controller B 29 Overview

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# **Two-phase step motors**

### MS 135/200 HT-2



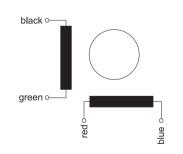
### General

Two-phase step motors behave similarly to synchronous motors. They are easy to control and are characterised by very long working life and reliability, at a favourable price. This results in a wide range of applications. Two-phase step motors in the MS range are of the high torque type. A particularly high torque is achieved by the use of rare earth magnets.

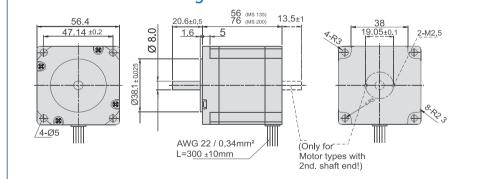
### **Technical specification**

| Description                 | Holding moment<br>bipolar<br><b>Nm</b> | Winding current per phase<br>A | Winding voltage<br>per phase<br>V | Winding inductance<br>per phase<br><b>mH</b> | Weight<br><b>kg</b> | Length<br>(without shaft)<br>mm | Part no.    |
|-----------------------------|----------------------------------------|--------------------------------|-----------------------------------|----------------------------------------------|---------------------|---------------------------------|-------------|
| MS 135 HT-2                 | 1.1                                    | 3.0                            | 2.4                               | 2.4                                          | 0.7                 | 56                              | 470551      |
| MS 200 HT-2                 | 1.8                                    | 3.0                            | 3.0                               | 3.5                                          | 1.0                 | 76                              | 470581      |
| MS 200 HT-2 (2nd shaft end) | 1.8                                    | 3.0                            | 3.0                               | 3.5                                          | 1.1                 | 76                              | 470581 0100 |
| MS 200 HT-2 (brake)         | 1.8                                    | 3.0                            | 3.0                               | 3.5                                          | 1.8                 | 76                              | 470581 0200 |

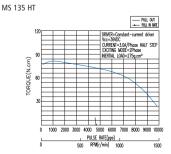
### Wiring diagram



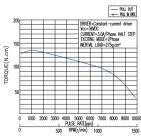
### Dimensioned drawing



### **Torque curves**



MS 200 HT



# **Two-phase step motors**

### MS 300/600/900 HT-2



### **Features**

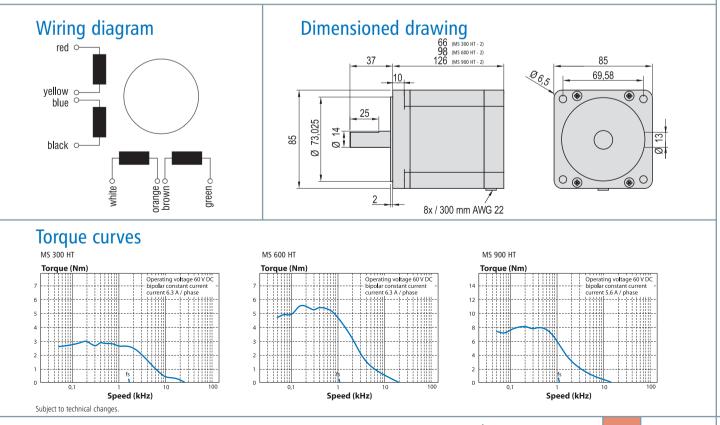
- Step angle 1.8°, higher resolution through microstep mode
- Very high torque through rare earth magnets
- Optimised for use with position controllers
- Optimum torque/size ratio
- 8-lead connection
- Smaller step angle errors, non-cumulative
- IP43 protection class
- Optional: MD 28 drive module

### General

Two-phase step motors behave similarly to synchronous motors. They are easy to control and are characterised by very long working life and reliability, at a favourable price. This results in a wide range of applications. Two-phase step motors in the MS range are of the high torque type. A particularly high torque is achieved by the use of rare earth magnets.

### **Technical specification**

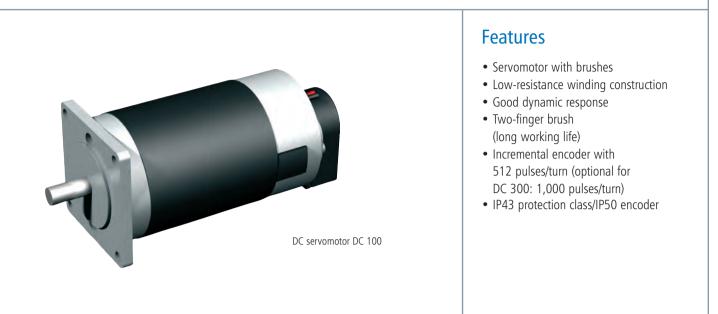
| Description   | Holding torque<br><sup>Bipolar</sup><br><b>Nm</b> | Winding current per<br>phase<br>parallel/series<br><b>A</b> | Winding voltage<br>per phase<br>parallel/series<br>V | Winding<br>inductance<br>per phase<br><b>mH</b> | Weight<br><b>kg</b> | Length<br>(without shaft)<br><b>mm</b> | Part no. |
|---------------|---------------------------------------------------|-------------------------------------------------------------|------------------------------------------------------|-------------------------------------------------|---------------------|----------------------------------------|----------|
| MS 300 HT - 2 | 3.11                                              | 5.6 / 2.8                                                   | 1.68 / 3.38                                          | 1.6                                             | 2.0                 | 66                                     | 470821   |
| MS 600 HT - 2 | 6.80                                              | 7.0 / 3.5                                                   | 2.28 / 4.55                                          | 2.4                                             | 3.0                 | 98                                     | 470851   |
| MS 900 HT - 2 | 9.00                                              | 6.3 / 3.1                                                   | 2.84 / 5.67                                          | 4.2                                             | 4.5                 | 126                                    | 470881   |



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### Servomotors with brush drive

# **DC 100**

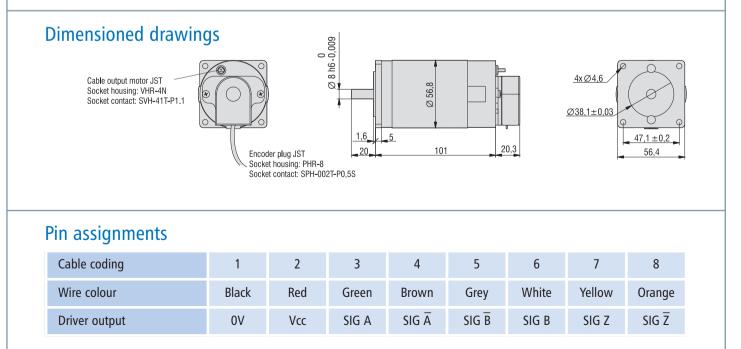


### General

DC servomotors with brushes are the entry into the controlled drive technology class. They have good dynamic response and have proved themselves in drive systems. The attached encoder enables precise positioning. This predestines their use in CNC machines and in automation systems.

### **Technical specification**

| Description | Voltage<br>V | No-load speed<br><b>rpm</b> | No-load cur-<br>rent<br>A | Rated speed <b>rpm</b> | Rated torque<br>Ncm | Rated cur-<br>rent<br>A | Rated output<br>W | Peak current<br>A | Part no.    |
|-------------|--------------|-----------------------------|---------------------------|------------------------|---------------------|-------------------------|-------------------|-------------------|-------------|
| DC 100      | 48           | 3,400                       | 0.25                      | 3,000                  | 30                  | 2.8                     | 95                | 6.5               | 471022 0020 |



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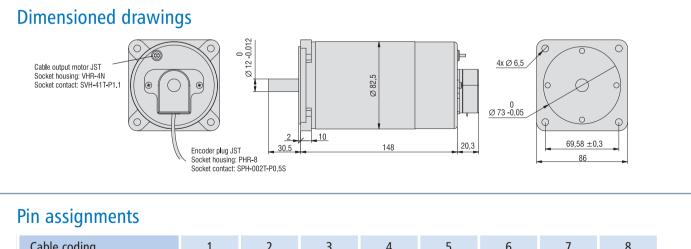


### General

DC servomotors with brushes are the entry into the controlled drive technology class. They have a good dynamic response and have proved themselves in drive systems. The attached encoder enables precise positioning. This predestines their use in CNC machines and in automation systems.

### **Technical specification**

| Description | Voltage<br>V | No-load speed<br><b>rpm</b> | No-load cur-<br>rent<br>A | Rated speed <b>rpm</b> | Rated torque<br>Ncm | Rated cur-<br>rent<br>A | Rated output<br>W | Peak current<br>A | Part no. |
|-------------|--------------|-----------------------------|---------------------------|------------------------|---------------------|-------------------------|-------------------|-------------------|----------|
| DC 300      | 48           | 3,200                       | 1                         | 3,000                  | 100                 | 9                       | 315               | 20                | 471024   |



| Cable coding  | 1     | 2   | 3     | 4     | 5                  | 6     | 7      | 8      |
|---------------|-------|-----|-------|-------|--------------------|-------|--------|--------|
| Wire colour   | Black | Red | Green | Browm | Grey               | White | Yellow | Orange |
| Driver output | 0V    | Vcc | SIG A | SIG Ā | SIG $\overline{B}$ | SIG B | SIG Z  | SIG Z  |

Subject to technical changes

isel<sup>®</sup>

| Sei  | vomotors        |
|------|-----------------|
| with | brushless drive |

## **EC 60**

# la la

### Features

- Electronically commutated 3-phase servomotor
- Brushless drive
- High output performance concurrently with compact build
- Incremental measuring system
- Hall sensors
- IP44 protection classUses: Positioning
- controllers, speed control
- Connection via circular plug
- Option: Brake

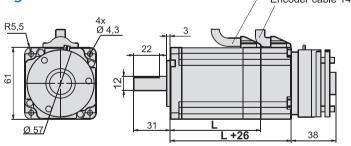
### General

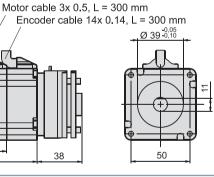
Brushless EC motors are designed as electronically switched 3-phase synchronous motors. Compared with brush drives, these motors have an even longer working life, because they are subjected to less wear. Moreover, in this case, high power density and dynamic response relative to size must be emphasized. These motors are used in many automation technology areas and in CNC machines.

### **Technical specification**

| Part no.    | Description       | Rated output<br>W | Rated voltage<br>V DC | Current<br>A | Number<br>of poles | Rated speed <b>rpm.</b> | Torque<br>at rated speed<br><b>Nm</b> | Peak<br>torque<br><b>Nm</b> | Length<br><b>L (mm)</b> | Weight<br><b>kg</b> |
|-------------|-------------------|-------------------|-----------------------|--------------|--------------------|-------------------------|---------------------------------------|-----------------------------|-------------------------|---------------------|
| 474156 0048 | EC 60S            | 156               | 48                    | 6.9          | 8                  | 3,000                   | 0.5                                   | 1.75                        | 73                      | 1.25                |
| 474156 1048 | EC 60S with brake | 156               | 48                    | 6.9          | 8                  | 3,000                   | 0.5                                   | 1.75                        | 73                      | 2.0                 |
| 474235 0048 | EC 60L            | 235               | 48                    | 10.5         | 8                  | 3,000                   | 0.75                                  | 2.25                        | 94                      | 1.6                 |
| 474235 0310 | EC 60L            | 235               | 310                   | 1.6          | 8                  | 3,000                   | 0.75                                  | 2.25                        | 94                      | 1.6                 |
| 474235 1310 | EC 60L with brake | 235               | 310                   | 1.6          | 8                  | 3,000                   | 0.75                                  | 2.25                        | 94                      | 2.35                |

### **Dimensioned drawings**





### Pin assignments

| Encoder cable |
|---------------|
|---------------|

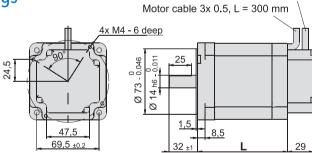
| PIN | Colour       | Signal      | PIN | Colour | Signal      |
|-----|--------------|-------------|-----|--------|-------------|
| 1   | yellow       | HALL_A_IN   | 9   | white  | HALL_B_IN   |
| 2   | red          | VCC_Encoder | 10  | black  | GND_Encoder |
| 3   | orange/black | /ENC_Z      | 11  | orange | ENC_Z       |
| 4   | brown/black  | /ENC_B      | 12  | brown  | ENC_B       |
| 5   | grey/black   | /ENC_A      | 13  | grey   | ENC_A       |
| 6   |              | _           | 14  | green  | HALL_C_IN   |
| 7   |              | -           | 15  |        |             |
| 8   |              | _           |     |        |             |

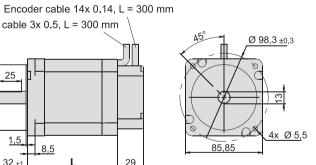
| Motor cable |         |  |  |  |  |
|-------------|---------|--|--|--|--|
| Colour      | Signal  |  |  |  |  |
| yellow      | Motor U |  |  |  |  |
| blue        | Motor V |  |  |  |  |
| green       | Motor W |  |  |  |  |

| Servomotors<br>with brushless drive                       | EC 86                                                                                                                                                                                                                                                                                                                                                                                                  | elec    |
|-----------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------|
|                                                           | <ul> <li>Features</li> <li>Electronically commutated<br/>3-phase servomotor</li> <li>Brushless drive</li> <li>High output performance<br/>concurrently with compact build</li> <li>Incremental measuring system</li> <li>Hall sensors</li> <li>IP44 protection class</li> <li>Uses: Positioning<br/>controllers, speed control</li> <li>Connection via circular plug</li> <li>Option: Brake</li> </ul> | tronics |
| motors have an even longer working life, because they are | hed 3-phase synchronous motors. Compared with brush drives, these<br>subjected to less wear. Moreover, in this case, high power density and<br>ese motors are used in many automation technology areas and in CNC                                                                                                                                                                                      |         |
| Technical specification                                   |                                                                                                                                                                                                                                                                                                                                                                                                        |         |
| Rated output Rated voltage Currer                         | Torque<br>nt Number Rated speed at Peak Length Weight                                                                                                                                                                                                                                                                                                                                                  |         |

| Part no.    | Description | Rated output<br>W | Rated voltage<br>V DC | Current<br>A | Number<br>of poles | Rated speed | Torque<br>at<br>rated speed<br><b>Nm</b> | Peak<br>torque<br><b>Nm</b> | Length<br>L<br><b>mm</b> | Weight<br><b>kg</b> |
|-------------|-------------|-------------------|-----------------------|--------------|--------------------|-------------|------------------------------------------|-----------------------------|--------------------------|---------------------|
| 474440 0310 | EC 865      | 440               | 310                   | 3.4          | 8                  | 3,000       | 1.4                                      | 5.0                         | 100                      | 2.6                 |
| 474660 0310 | EC 86L      | 660               | 310                   | 3.6          | 8                  | 3,000       | 2.1                                      | 7.4                         | 125                      | 4                   |







# Pin assignments

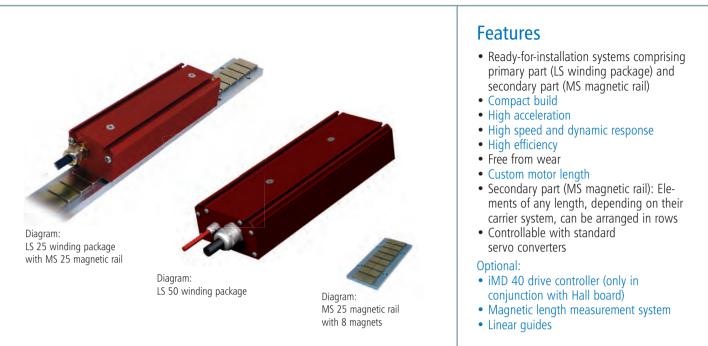
| Encoder c | able         |             |     |        |             |
|-----------|--------------|-------------|-----|--------|-------------|
| PIN       | Colour       | Signal      | PIN | Colour | Signal      |
| 1         | yellow       | HALL_A_IN   | 9   | white  | HALL_B_IN   |
| 2         | red          | VCC_Encoder | 10  | black  | GND_Encoder |
| 3         | orange/black | /ENC_Z      | 11  | orange | ENC_Z       |
| 4         | brown/black  | /ENC_B      | 12  | brown  | ENC_B       |
| 5         | grey/black   | /ENC_A      | 13  | grey   | ENC_A       |
| 6         |              | -           | 14  | green  | HALL_C_IN   |
| 7         |              | -           | 15  |        |             |
| 8         |              | -           |     |        |             |

| Motor ca | ble     |
|----------|---------|
| Colour   | Signal  |
| yellow   | Motor U |
| blue     | Motor V |
| green    | Motor W |
|          |         |

# Linear motors

LS coil package with MS magnetic rail

# iLM series



### General

Linear motors in the iLM series are linear 3-phase servomotors of various sizes and any length at a favourable price/performance ratio. The optionally integrated Hall sensors provide the positional information for switching the motor. There is a PTC temperature sensor in the primary component to protect the motor. The electrical connections (Hall, windings and temperature sensor) are made via permanently installed cable. Owing to the direct power transfer, there is no need for any mechanical transfer elements, such as spindles and toothed belts which completely eliminates friction and play. This means that higher speeds and dynamic responses can be achieved. The resultant lower clocking times reduce production costs and increase productivity. Because there are no mechanical elements in the drive itself, noise, wear and the resultant maintenance costs are minimised. In comparison with other linear drives, drives with linear motors are more accurate, faster, free from play (without return play) and more robust.

### Ordering information

Winding package

### 486 0XX 000X

| Coil package     |                               | Number of coils $1 = 3$ coils |
|------------------|-------------------------------|-------------------------------|
| <b>0</b> = LS 25 | Hall boards                   | 2 = 6 coils                   |
| 1 = LS 50        | <b>0</b> = without Hall board | 3 = 9 coils                   |
|                  | 1 = with Hall board           | 4 = 12 coils                  |

Note:

For the iMD 40 drive controller use coil packages with Hall boards only. Any number of magnetic rails can be arranged with each other.

Ordering example

+ iMD 40 drive controller

### Magnetic rails

MS 25 magnetic rail with 8 magnets (L×W×H approx.124/45/11mm) Part no.: 486100 01241

MS 25 magnetic rail with 32 magnets (L $\times$ W $\times$ H approx.496/45/11 mm) Part no.: 486100 04961

MS 50 magnetic rail with 8 magnets (L $\times$ W $\times$ H approx. 200/80/11 mm) Part no.: 486110 0200

MS 50 magnetic rail with 16 magnets (L $\times$ W $\times$ H approx. 400/80/11 mm) Part no.: 486110 0400

MS 50 magnetic rail with 32 magnets (L $\times$ W $\times$ H approx. 800/80/11 mm) Part no.: 486110 0800

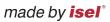
Part no.: 486001 0002 Part no.: 486100 0496 Part no.: 314040 Part no.: 390255 4412

Subject to technical changes

+ iMS-I magnetic length measuring system (5  $\mu$ m resolution)

LS 25 coil package with 6 coils and Hall boards

+ 2 $\times$  MS 25 magnetic rails with 32 magnets



**iLM** series

### **Linear motors** LS coil package with MS magnetic rail

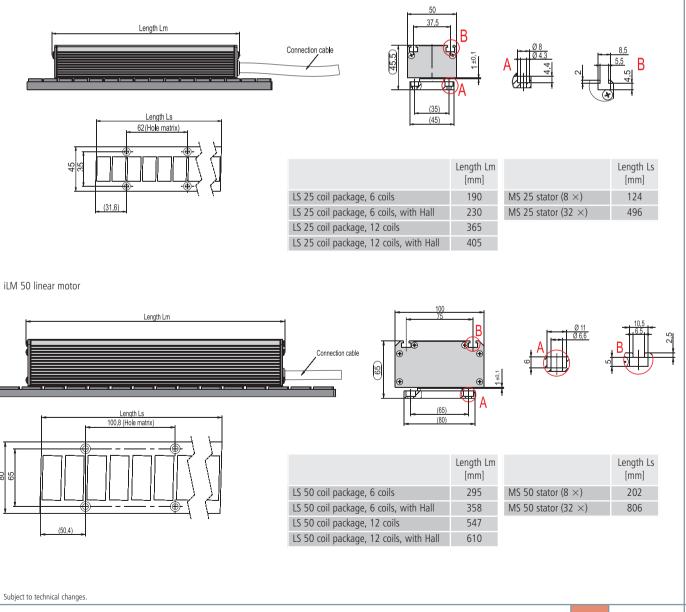
### **Technical specification**

|               | Intermediate circuit<br>voltage [V] ** | Number<br>of coils | Rated current<br>[A] | Peak current<br>[A] | Feed force [N] | max. feed force [N] | max. tensile force<br>[N]* | Rated speed<br>[m/s]<br>at rated current |
|---------------|----------------------------------------|--------------------|----------------------|---------------------|----------------|---------------------|----------------------------|------------------------------------------|
| LS 25/6 coils | 330                                    | 6                  | 2.6                  | 6.5                 | 70             | 170                 | 500                        | 6.6                                      |
| LS 25/12 coi  | s 330                                  | 12                 | 2.6                  | 6.5                 | 140            | 340                 | 1,000                      | 4.0                                      |
| LS 50/6 coils | 330                                    | 6                  | 6.0                  | 15.0                | 285            | 675                 | 1,995                      | 5.1                                      |
| LS 50/12 coi  | s 330                                  | 12                 | 6.0                  | 15.0                | 570            | 1,350               | 3,990                      | 3.5                                      |

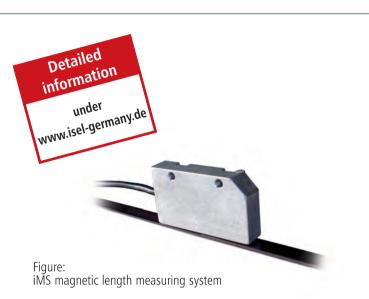
\* Higher intermediate circuit voltage to order. \*\* Applicable for a working air gap of 0.8 mm.

# **Dimensioned drawings**

iLM 25 linear motor



# iMS magnetic length measuring system



### General

The iMS contactless magnetic measuring system relies on scanning a magnetically coded measuring tape by means of a magnetically sensitive sensor and is suitable for detection of both linear and radial positions. A decisive advantage compared with significantly more expensive optical systems is provided by its insensitivity to contamination caused by liquids, greases and dust. Our length measuring system is therefore a cost-effective alternative to other systems on the market.

Available sensor interfaces for further processing in the peripherals are, optionally, a pulse sensor with incremental RS422 AB output (Z optional) and a SIN/COS/(Z optional) sensor with voltage amplitude 1Vss.

### Features

- Measuring head with sensor in stable casing
- Reliable, robust, good value
  2 channels, A and B, Difference mode incremental RS 422 or
- Difference mode analogue 1VSS • Incremental/digital resolution (see table)
- Repeatability =  $\pm 1$  increment
- Magnetic tape on self-adhesive, stainless steel bearer tape

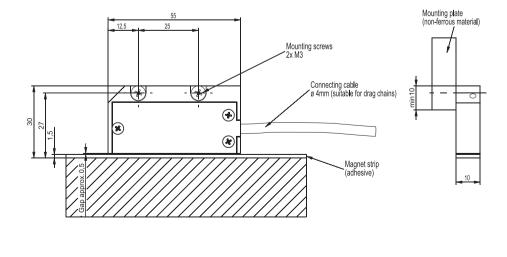
### optional:

• Reference pulse

### Ordering information

iMS-I magnetic length measuring system in casing Resolution 5 $\mu$ m, edge interval 0.55  $\mu$ s, Processing speed 5.25 m/s Part no.: **390255 4412** 

Magnetic tape on self-adhesive stainless steel bearer tape (2 mm pole pitch, 10 mm wide, 1.3 mm thick) Part no.: 563150



### **Dimensioned drawing**

made by isel®

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ectronic

# iMS magnetic length measuring system

### Technical specification

### Sensor

| Mechanical specification        |                                                                                                                |  |  |  |
|---------------------------------|----------------------------------------------------------------------------------------------------------------|--|--|--|
| Casing                          | Aluminium                                                                                                      |  |  |  |
| Weight                          | appr. 70 g                                                                                                     |  |  |  |
| Sensor cable                    | PUR                                                                                                            |  |  |  |
| Cable bending radius            | >10 mm, first bend $>$ 10 mm from sensor casing                                                                |  |  |  |
| Electronic data                 |                                                                                                                |  |  |  |
| Supply voltage                  | 4.9V - 5.1V<br>(optional: 7V - 15V)                                                                            |  |  |  |
| Current drain                   | < 100 mA on no load                                                                                            |  |  |  |
| Output signals                  | Standard RS422 A, /A, B, /B optional reference Z, /Z Option: SIN/ COS 1Vss $+20\%$ , -40%, Z and /Z right sign |  |  |  |
| Termination                     | Terminating resistor = 120 Ohm between corresponding output signals,<br>e.g. A - /A, at receiver               |  |  |  |
| Sensor distance - magnetic tape | 0.4 - 0.7 mm                                                                                                   |  |  |  |
| Sensor resolution incremental   | 1 μm, 2.5 μm, 5 μm, 10 μm, 20 μm                                                                               |  |  |  |
| Pulse interval                  | 0.25 μs, 0.55 ns, 1 μs, 2 μs, 4 μs, 8 μs                                                                       |  |  |  |
| Analogue sensor resolution      | Sinusoidal period length $= 2 \text{ mm}$                                                                      |  |  |  |
| maximum speed                   | < 10 m/s, higher on request                                                                                    |  |  |  |
| Repeatability                   | Incremental resolution $\pm$ 1 increment, plus errors due to angular tilting in the 3 sensor axes              |  |  |  |
| Accuracy                        | Measurement error 20 $\mu$ m, plus errors due to angular tilting in the 3 sensor axes                          |  |  |  |
| Reference sequence              | optional: NSN (special order)                                                                                  |  |  |  |
| Ambient conditions              |                                                                                                                |  |  |  |
| Operating temperature           | -5°C to 80°C                                                                                                   |  |  |  |
| Storage temperature             | -20°C to 100°C                                                                                                 |  |  |  |
| Air humidity (only sensor)      | 100%, dewing allowed                                                                                           |  |  |  |

### Normal measurement - magnetic strip

| Operating temperature                                  | -5°C to 80°C                                                                                                                                                                                                                                                                                                                                                                                   |
|--------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Material                                               | High quality stainless steel, coding bearer elastomer, self-adhesive                                                                                                                                                                                                                                                                                                                           |
| Thickness                                              | 1.3 mm $\pm$ 0.15 mm $+$ bonding layer 0.13 mm, optional: 0.1 mm stainless steel tape $+$ bonding view 0.2 mm                                                                                                                                                                                                                                                                                  |
| Width                                                  | 10 mm                                                                                                                                                                                                                                                                                                                                                                                          |
| Length                                                 | up to 50 m on roll                                                                                                                                                                                                                                                                                                                                                                             |
| Pole pitch/PITCH                                       | 2 mm, i.e. north pole = 2 mm, south pole = 2 mm<br>magnetic period = 4 mm                                                                                                                                                                                                                                                                                                                      |
| Number of tracks                                       | Single track, 10 mm wide<br>Option: signal track 5 mm, reference track periodically 5 mm                                                                                                                                                                                                                                                                                                       |
| Accuracy                                               | $\pm$ 0.04 mm/m up to 50 m length, at 20°C                                                                                                                                                                                                                                                                                                                                                     |
| Coefficient of expansion                               | 17E-6 m/Kelvin                                                                                                                                                                                                                                                                                                                                                                                 |
| Ambient conditions                                     |                                                                                                                                                                                                                                                                                                                                                                                                |
| with no or minimum effect on the measurement norm      | Chemical resistance to contamination with motor oil, gearbox oil, ATF, hydraulic oil, kerosene, antifreeze, Clorox disinfectant, turpentine, water, brine. The materials listed have no or little effect on the long term stability of the measurement standard; among others, it depends on the concentration, the temperature and the time of the contamination. Please check your own case. |
| little/average effect on the measure-<br>ment standard | Jet petrol, carburettor fuels, heptanes, alcohols                                                                                                                                                                                                                                                                                                                                              |
| serious effect on the measurement standard             | Aromatic hydrocarbons, ketones, inorganic acids                                                                                                                                                                                                                                                                                                                                                |

Subject to technical changes.

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# **CNC control panels**

# iBP 19



### General

CNC control panels are robust and powerful control units for an extensive range of applications in industrial automation and much more.

A conventional external PC can be connected and operated with the standard connections provided. All CNC control panels come with an integrated touch screen monitor, a keyboard and a control panel with stainless steel keys and 2-channel emergency shutdown switch for operating

CNC machines The extensive range of installation options cater to both wall and bench mounting. Three different versions are available.

### Ordering information

| 19" CNC control panel iBP 19-1, German silicon keyboard  | Part no.: 371076 0102 |
|----------------------------------------------------------|-----------------------|
| 19" CNC control panel iBP 19-1, English silicon keyboard | Part no.: 371076 0112 |
| 19" CNC control panel iBP 19-2, German steel keyboard    | Part no.: 371077 0102 |
| 19" CNC control panel iBP 19-2, English steel keyboard   | Part no.: 371077 0112 |
| Mounting arm for wall mounting iBP 19                    | Part no.: 371050 0003 |
| Mounting arm for bench mounting                          | Part no.: 371050 0004 |
| Stand iBP 19                                             | Part no.: 371050 0005 |
| Mounting arm for rack assembly iBP 19 on PS 80           | Part no.: 371050 0009 |
| Mounting arm for rack assembly iBP 19 on PS 100          | Part no.: 371050 0010 |
| Mounting arm for rack assembly iBP 19 on PS 140          | Part no.: 371050 0008 |

### Features

### iBP 19-1

- 19" TFT touch screen display
- 102 keys, silicon keyboard (IP65) with integrated 2-key mouse pointer or mouse carrier plate fixed to the side
   Dimensions:
- 475 x D 501 x H 354 mm
- Weight: appr. 17.4 kg

### iBP 19-2

- 19" TFT touch screen display
- 102 keys, stainless steel keyboard (IP65) with integrated 2-key trackball
- Dimensions: W 475 x T 501 x H 354 mm
- Weight: appr. 18.4 kg

### **Common features**

- stable metal casing with aluminium front plate
- pivoted with wall and bench mounting
- simple connection of external PC systems
- Touch screen monitor
- robust and tamper-proof casing
- Control panel with stainless steel keys
- 2-channel emergency shutdown switch

### Option:

• English keyboard

# Drive modules

for 2-phase step motors

# Features

- High performance, low noise
- Power supply up to 50 V DC (80V DC)\*
- Output current up to 4.2 A (7.8 A)\*
- Automatic current reduction
- Suitable for 2-phase and 4-phase step motors
- Clocking/direction interface
- Input frequency for clocking input up to 300 KHz
- 15 (14)\* selectable resolutions up to 25,600 steps/rev (51,200 steps/rev)\*
- Opto-isolated, TTL-compatible inputs
- Protection against short-circuit, overvoltage and overcurrent

\* MD 28

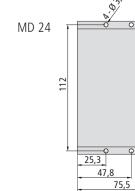


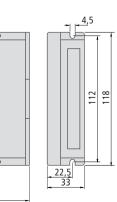
The step motor drive modules MD24/MD28 are powerful final stages for 2-phase and 4-phase step motors. The modules are micro-step capable and thus allow very quiet running of the connected motors. Due to its particular chopper technology for the motor current, identical motors can deliver higher speeds and torques than conventional comparable drive modules. The clocking/direction interface also allows simple connection to various motion controllers or a PLC.

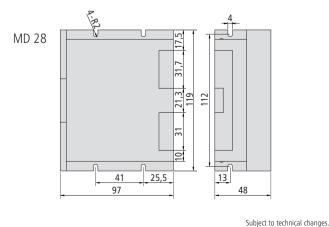
### **Technical specification**

| Min.<br>1.0<br>20 | Typical<br>-<br>36 | Max.<br>4.2 (3.0 A RMS) | Min.<br>2.8    | Typical<br>-             | Max.<br>7.8                |  |
|-------------------|--------------------|-------------------------|----------------|--------------------------|----------------------------|--|
|                   |                    |                         |                | -                        | 7.8                        |  |
| 20                | 36                 | 50                      |                |                          |                            |  |
|                   | 20                 | 50                      | 24             | 68                       | 80                         |  |
| 7                 | 10                 | 16                      | 7              | 10                       | 16                         |  |
| 0                 | -                  | 300                     | 0              | -                        | 300                        |  |
| 500               |                    |                         | 500            |                          |                            |  |
|                   | 316303             |                         |                | 316304                   |                            |  |
|                   | -                  | 0 -<br>500              | 0 - 300<br>500 | 0 - 300 0<br>500 500 500 | 0 - 300 0 -<br>500 500 500 |  |

### **Dimensioned drawings**







### 



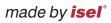
### General

The **iMD10/20/30** series of drive controllers are economical final stages for DC motors (iMD10) and EC servomotors (iMD20) as well as for two-phase step motors (iMD30). The fully digital **iMD40** drive controller is an economical final stage, powered directly from the mains, for EC servomotors (synchronous motors, such as linear or torque motors) up to 2 kW.

Typical applications are CNC machines and automation systems. The final stage casings are optimised for cabinet installation. The extensive configuration options allow flexible adaptation to a wide range of applications and all required settings can be made with a user-friendly commissioning software package.

There are various user interfaces available for integration with proprietary applications. Here, the CAN open interface must be emphasized. In addition to synchronous point-to-point positioning (S-PTP) and speed control, track control (CP -Continuous Path) and synchronised multiple axis applications are feasible using the implemented CANopen protocol DS402. Additional interfaces include a  $\pm$ 10V interface (nominal speed) and a RS232 interface. The iMD30 also has a clocking/direction interface.

Short controller cycle times (current, speed, position controller) ensure optimum performance for highly dynamic drives. The drive controllers are suitable both for rotary drives and for the corresponding linear direct drives and torque motors (iMD20 and iMD40). A redundant rest monitoring system has been integrated in the drive controller. It reduces work by the controller in external assemblies to a minimum and allows for convenient operation or use of the machine.



iMD 10/20/30/40

# **Drive controllers**

for multi-phase and servomotors

### Technical specification

| Features                                                     | iMD 10                                                                                               | iMD 20                                                                                               | iMD 30                                                                                              | iMD 40                                                                                             |  |
|--------------------------------------------------------------|------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------|--|
| Motor type                                                   | Brush<br>servomotors (DC)                                                                            | Brushless servomotors<br>(EC, BLDC)                                                                  | Two-phase<br>step motors (ST)                                                                       | Brushless<br>servomotors (DC, BLDC)                                                                |  |
| Power supply                                                 |                                                                                                      | 40-95 V DC                                                                                           |                                                                                                     | 230V AC, mains, single phase                                                                       |  |
| Motor current                                                | Constant current 1                                                                                   | 2 A, peak current 25 A                                                                               | Constant current 12 A                                                                               | Constant current 6.5 A<br>Peak current 8 A                                                         |  |
| CAN bus interface                                            | CANopen DS301 V4.0 and DS402 V1.0 d                                                                  |                                                                                                      | er CiA (CAN in automation)                                                                          | CANopen DS301 V4.0 and<br>DS402 V1.0 of CiA<br>(CAN in automation)                                 |  |
| RS-232 interface<br>(asynchronous, 19.2 or<br>57.6 kbits/s). | For commissioning<br>(DcSetup.exe) or<br>e.g. PLC connection;<br>effective data<br>transfer protocol | For commissioning<br>(AcSetup.exe) or<br>e.g. PLC connection;<br>effective data<br>transfer protocol | For commissioning<br>(StepSetup.exe) or<br>e.g. PLC connection;<br>effective data transfer protocol | For commissioning<br>(AcSetup.exe) or, e.g. PLC<br>connection; effective data<br>transfer protocol |  |
| Measuring system                                             | Incremental encoder (RS422);<br>max. input frequency: 1.25 MHz                                       |                                                                                                      |                                                                                                     | Incremental encoder<br>(RS422); max. input fre-<br>quency: 1.25 MHz                                |  |
| Commutation                                                  |                                                                                                      | Hall sensor signals                                                                                  |                                                                                                     | Hall sensor signals                                                                                |  |
| Analogue input ( $\pm 10V$ )                                 |                                                                                                      | 11 bit resolutio                                                                                     | n                                                                                                   | 11 bit resolution                                                                                  |  |
| PWM switching frequency                                      | max. 12.5 kHz                                                                                        | max. 16.4 kHz                                                                                        | max. 10.0 kHz                                                                                       | max. 16.4 kHz                                                                                      |  |
| Inputs for<br>limit and<br>reference switches                | √                                                                                                    | 1                                                                                                    | ✓                                                                                                   | 1                                                                                                  |  |
| Digital current,<br>speed and<br>position control            | Scanning times:<br>min. 80 µs/244 µs/<br>488 µs for<br>current/speed/posi-<br>tion controllers       | Scanning times:<br>min. 61 µs/244 µs/<br>488 µs for<br>current/speed/position<br>controllers         | Scanning times:<br>min. 100 $\mu$ s for current control-<br>lers                                    | Scanning times: min.<br>61µs/<br>244 µs/488 µs for current/<br>speed/position controllers          |  |
| Brake controller                                             | $\checkmark$                                                                                         | $\checkmark$                                                                                         | $\checkmark$                                                                                        | $\checkmark$                                                                                       |  |
| Gantry mode or synchronous control                           |                                                                                                      | of 2 modules                                                                                         | s, Master-Slave via CAN bus                                                                         |                                                                                                    |  |
| Monitoring of the motor current                              | Short circuit, I <sup>2</sup> t                                                                      | Short circuit, l <sup>2</sup> t,<br>Pulse-by-pulse                                                   | Short circuit                                                                                       | Short circuit, l <sup>2</sup> t,<br>Pulse-by-pulse                                                 |  |
| Monitoring of the encoder signals                            | $\checkmark$                                                                                         | $\checkmark$                                                                                         |                                                                                                     | √                                                                                                  |  |
| Monitoring of the<br>software by<br>internal Watchdog timer  | V                                                                                                    | √                                                                                                    | $\checkmark$                                                                                        | ✓                                                                                                  |  |
| Simple update of the firmware over RS-232                    | Possible locally by customer or service engineer                                                     |                                                                                                      |                                                                                                     |                                                                                                    |  |
| Rest state monitoring                                        |                                                                                                      | Redund                                                                                               | dancy to ISO standard                                                                               |                                                                                                    |  |
| Dimensions                                                   | 180 x 35 x 110 mm                                                                                    | 180 x 35 x 120 mm                                                                                    | 180 x 35 x 110 mm                                                                                   | 180 x 50 x 150 mm                                                                                  |  |
| Part no.<br>Drive controllers                                | 314 020                                                                                              | 314 030                                                                                              | 314 070                                                                                             | 314 040                                                                                            |  |

# **Motion Kits**

# iMK



### **Technical specification**

| reennear speenrearion                 |                                                         |             |               |             |  |
|---------------------------------------|---------------------------------------------------------|-------------|---------------|-------------|--|
|                                       | iMK 20S                                                 | iMK 20L     | iMK 40S       | iMK 40L     |  |
| Motor type                            | EC 60 S                                                 | EC 60 L     | EC 86 S       | EC 86 L     |  |
| Motor output [W]                      | 157                                                     | 235         | 440           | 660         |  |
| Rated torque [Nm]                     | 0.5                                                     | 0.75        | 1.4           | 2.1         |  |
| Peak torque [Nm]                      | 1.75                                                    | 2.25        | 5.0           | 7.5         |  |
| Rated speed [rpm]                     | 3,000                                                   |             |               |             |  |
| Encoder resolution [incr]             | 1,000                                                   |             |               |             |  |
| Power supply                          | 40-95 V DC 230 V AC                                     |             |               |             |  |
| CAN bus interface                     | CANopen DS301, DS402 of CiA (CAN in automation)         |             |               |             |  |
| Analogue input ( $\pm$ 10V)           | 11 bit resolution                                       |             |               |             |  |
| PWM switching frequency               | 8.2 kHz or 16.4 kHz                                     |             |               |             |  |
| Current/speed/position controllers    | Scanning times min 61 $\mu$ s, 344 $\mu$ s, 488 $\mu$ s |             |               |             |  |
| Inputs for reference & limit switches | $\checkmark$                                            |             |               |             |  |
| Brake controller                      | $\checkmark$                                            |             |               |             |  |
| Gantry or synchronous operation       | $\checkmark$                                            |             |               |             |  |
| Motor current monitoring              | $\checkmark$                                            |             |               |             |  |
| Monitoring of encoder signals         | $\checkmark$                                            |             |               |             |  |
| Watchdog                              | $\checkmark$                                            |             |               |             |  |
| Galvanic isolation                    | Processor Power section, I/Os                           |             |               |             |  |
| Rest state monitoring                 | $\checkmark$                                            |             |               |             |  |
| Drive controller dimensions           | 180 x 35 :                                              | x 120 mm    | 180 x 50      | x 150 mm    |  |
| Part no. Drive controller and motor   | 317000 0002                                             | 317000 0003 | 317000 0004   | 317000 0005 |  |
| Part no. Motor cable                  | 392760                                                  | ) xxxx *    | 392305 xxxx * |             |  |
| Part no. Encoder cable                | 392740 xxxx *                                           |             |               |             |  |

\* Cable length in mm

available in different lengths.

e.g.: 0150 = 1.50 m 0200 = 2.00 m 0300 = 3.00 m 0500 = 5.00 m ... 1000 = 10.00 m

# **PC controller**



### **Technical specification**

|                                                               | iPC15 PC controller                                                                                                                                                                                                                                                                                                                                     |
|---------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| CPU                                                           | Intel <sup>®</sup> Atom N270                                                                                                                                                                                                                                                                                                                            |
| Form factor mainboard                                         | Mini-ITX (half height)                                                                                                                                                                                                                                                                                                                                  |
| RAM                                                           | DDR2 SO DIMM 1GB (up to 2GB)                                                                                                                                                                                                                                                                                                                            |
| Hard disks (S-ATA)                                            | 2,5" ≥ 160 GB                                                                                                                                                                                                                                                                                                                                           |
| Graphics                                                      | Intel GMA 950                                                                                                                                                                                                                                                                                                                                           |
| Monitor                                                       | VGA/DVI-D                                                                                                                                                                                                                                                                                                                                               |
| Audio                                                         | Realtek® ALC662 Audio Codec                                                                                                                                                                                                                                                                                                                             |
| LAN                                                           | 10/100/1,000 Mbit LAN                                                                                                                                                                                                                                                                                                                                   |
| Power supply                                                  | 12 V DC                                                                                                                                                                                                                                                                                                                                                 |
| External connections<br>(Basic version -<br>with blind panel) | 3 × USB 2.0, LAN<br>VGA, DVI-D<br>Audio multifunction connection<br>12V DC power supply                                                                                                                                                                                                                                                                 |
| Internal interfaces                                           | $\begin{array}{l} 1 \times \text{PCI (without CAN interface)} \\ 1 \times \min \text{PCI Express, } 1 \times \text{IDE} \\ 2 \times \text{SATA (1 x with HDD)} \\ 4 \times \text{USB 2.0 (3 \times with SSD),} \\ 1 \times \text{parallel interface,} \\ 2 \times \text{serial interface,} \\ 1 \times \text{PS/2, } 1 \times \text{SPDIF} \end{array}$ |
| Humidity                                                      | Max. 90% (not condensing)                                                                                                                                                                                                                                                                                                                               |
| Ambient temperature                                           | 0°C to 35°C                                                                                                                                                                                                                                                                                                                                             |
| Protection class                                              | IP 20                                                                                                                                                                                                                                                                                                                                                   |
| Weight                                                        | 1.1 kg                                                                                                                                                                                                                                                                                                                                                  |
| Dimensions (W $\times$ H $\times$ D)                          | 200 x 50 x 190 mm                                                                                                                                                                                                                                                                                                                                       |

# iPC 15

### General

The iPC15 universal PC controller is a Windows- or Linux-compatible controller at a favourable price/performance ratio. Its versatile applications may be found throughout the entire industry sector and in various consumer sectors.

All connections are made on the front. A multifunctional panel provides many potential variations in the connection area.

Inter alia, a CAN interface with optionally 1 or 2 channels is available.

A remote interface is available for covered installation (e.g. in a cabinet or in the interior of a motor vehicle).

Installation is possible both in the "standing" and "lying" positions.

### Features

- Universal PC controller
- Robust, impact-proof aluminium casing
- Compact configuration
- Various installation options
- Energy-efficient and low noise
- Supply voltage 12V DC
- Front multifunctional panel for versatile connection options
- Design with hard disk or
- solid state disk (optional)Windows- and Linux-compatible

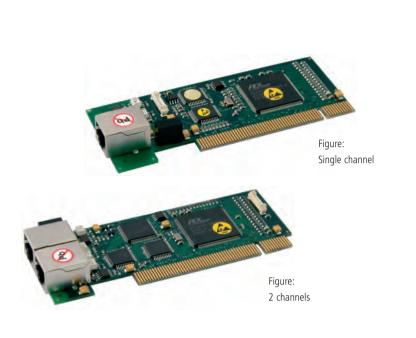
### Ordering information

iPC15 PC controller, CAN-PCI-1-channel, PCI riser board, serial, remote, including Windows, power supply unit and lead Part no.: **371064 0005** 

iPC15 PC controller, CAN-PCI-2-channel, PCI riser board, serial, remote, including Windows, power supply unit and lead Part no.: **371064 0006**  electronics

# **CAN PCI board**

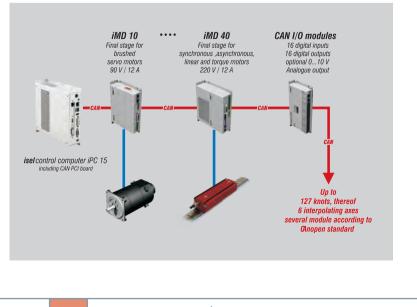
# iCC 10/20



### **Technical specification**

|                    | iCC 10/20         |  |
|--------------------|-------------------|--|
| Interface          | PCI V2.2 / 32 bit |  |
| CAN channels       | 1/2               |  |
| galvanic isolation | $\checkmark$      |  |
| Data transfer rate | up to 1 Mbits/s   |  |
| Plug               | RJ45              |  |

### Block diagram CAN bus with iPC 15



### General

CAN-PCI boards offer a simple solution for connecting a CAN bus to the PCI bus system of a PC. (e.g. iPC 15)

A driver software package is supplied with the board, which controls the entire CANopen communication with the application interface (e.g. ProNC) and also provides a programming interface for your own software.

The board can also be used in conjunction with CoDeSys V2.3.

The software package also includes configuration software which can be used to install the default settings for the CAN parameters (CANset).

### Features

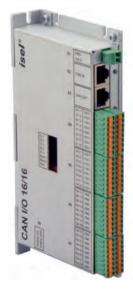
- Mechanical dimensions:  $119.5 \times 47.3 \text{ mm}$
- PCI-V2.2-compliant
- 32-bit, 33 MHz target interface chip
- 1 or 2 CAN channel RJ45 connector, screened
- CAN bus galvanically isolated
- Data transfer rate up to 1 Mbits/s
- Drivers for NT/2000/XP/Vista
- Driver for isel-CAN-CNC controller
- Driver for CoDeSys available
- PDO and SDO communication via supplied DLL
- can be used as CANopen master for a wide range of applications

### **Ordering information**

CAN PCI board iCC 10 Part no.: 320310 (Single channel)

CAN PCI board iCC 20 Part no.: 320311 (2 channels)

# **CAN controller components**





CAN I/0 module 16/16

CAN I/0 module 8/12 - 4/1

### **Technical specification**

|                        | CAN I/O module 16/16                                                                                                                       | CAN I/0 module 8/12 -4/1                                                                                                                   |  |
|------------------------|--------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------|--|
| Digital inputs         | 16 via optical coupler<br>(Input current approx. 8 mA)                                                                                     | 8 via optical coupler<br>(Input current approx. 8 mA)                                                                                      |  |
| Digital<br>outputs     | $\begin{array}{ll} 16 & 8 \times \text{relays, Imax} < 5 \text{A} \\ & 8 \times \text{electronically, Imax} < 350 \ \text{mA} \end{array}$ | $\begin{array}{ll} 12 & 4 \times \text{relays, Imax} < 5 \text{A} \\ & 8 \times \text{electronically, Imax} < 350 \ \text{mA} \end{array}$ |  |
| Analogue output        | 1 OV - 10V via<br>8-bit D/A converter<br>(when using the analogue output , the electronic<br>outputs are no longer available for use)      | 1 OV - 10V via<br>8-bit D/A converter                                                                                                      |  |
| Analogue input         | -                                                                                                                                          | 4 OV - 10V,<br>10-bit resolution                                                                                                           |  |
| Protection class       | IP20                                                                                                                                       |                                                                                                                                            |  |
| Supply<br>voltage      | 24V DC (logic voltage),<br>24V DC (process voltage),                                                                                       |                                                                                                                                            |  |
| Power<br>consumption   | 160 mA (logic and relays)<br>ILoad is dependent on the external wiring                                                                     |                                                                                                                                            |  |
| Ambient<br>temperature | -5°C to $+40$ °C                                                                                                                           |                                                                                                                                            |  |
| Storage temperature    | -25°C to +70 °C                                                                                                                            |                                                                                                                                            |  |
| Relative<br>humidity   | max 95 %                                                                                                                                   |                                                                                                                                            |  |
| Protection class       | IP20                                                                                                                                       |                                                                                                                                            |  |
| Weight                 | 260 g                                                                                                                                      |                                                                                                                                            |  |
| Casing size            | 85 $\times$ 180 $\times$ 28 mm (W $\times$ H $\times$ D)                                                                                   |                                                                                                                                            |  |
| Part no.               | 321002                                                                                                                                     | 321004                                                                                                                                     |  |

### General

Both isel CANopen I/O modules provide an entry level into the world of modern industrial automation. They enable installation on site or in a cabinet.

A 24V DC power supply, galvanic isolation of the inputs and outputs and the terminals available directly on the module provide a great range of operating possibilities.

Connection via plug-in terminals and the status display assigned directly to the connection make for very userfriendly installation and servicing.

### Features

### CAN I/0 module 16/16

- 16 digital inputs via optical couplers (input current approx. 8 m A)
- 16 digital outputs, 8 × relays, Imax < 5A, 8 × electronically, Imax < 350 mA (thermal protection, short circuit protection)
- One analogue output, OV 10V via 8-bit D/A converter (users of an analogue output can no longer use the electronic outputs)

### CAN I/0 module 8/12 - 4/1

- 8 digital inputs via optical couplers (Input current approx. 8 m A)
- 12 digital outputs,  $4 \times$  relays, Imax < 5A,  $8 \times$  electronically, Imax < 350 mA (thermal protection, short circuit protection)
- One analogue output, OV 10V via 8-bit D/A converter
- 4 analogue outputs, 0V 10V 10-bit resolution

Subject to technical changes.

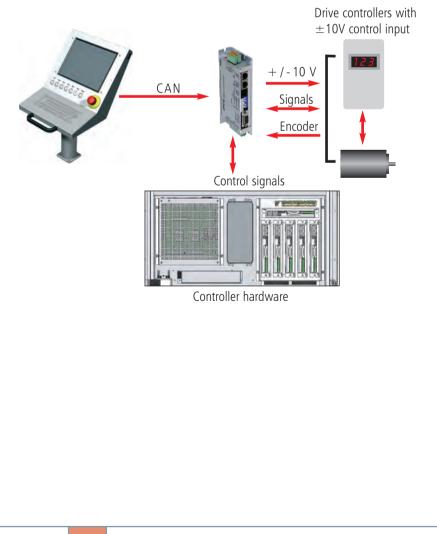
made by **isel**°

# **CAN controller components**



Universal CAN positioning module CPC 12, with  $\pm$  10V output

### **Application diagram**



### General

The CAN CPC12 positioning module serves adaptation of drive controllers from various other manufacturers with  $\pm$ 10V interface to the CAN CNC controller.

This enables - in addition to CAN drive controllers offered by isel - operation of not CAN-enabled modules or modules that are not directly compatible with this controller.

The necessary control inputs and outputs for this purpose are provided by the CPC12 module.

### Features

### CAN CPC 12 positioning module

- Controlling any number of drive controllers and frequency converters with ± 10V input
- Digital position control with cycle time 488  $\mu s$
- Power supply +24V DC
- CANopen DS 301, DS 402, data transfer rate up to 1 Mbd
- RS232 for commissioning or PLC coupling
- Outputs for releasing external servo controllers and brake controllers
- Inputs for reference & limit switches
- Incremental encoder (RS422)
- Monitoring of limit switches for the positioning axes with emergency shutdown message
- Optionally as multi-axis solution in control cabinet
- Gantry mode or synchronous control of 2 modules, Master-Slave via CAN bus

Part no.: 320 210

```
Subject to technical changes
```

# **Step controller**

Single axis controller



Figure: IT 116 Flash back side

### General

The IT 116 Flash step controller is a freely programmable compact controller for a linear or circular axis with 2-phase step motor. The step controller comprises an intelligent step motor stage, a processor core with Flash memory for downloading/storing the PAL-PC user program and the clocking/direction signal generation for the final stage of the motor, the necessary power supply units, a safety circuit (Stop category 0 to EN 60204) and a casing with mains input filter and control elements.

The integrated operating system in the Flash memory of the processor core supports both

• the DNC mode of the controller: PC/laptop connected permanently with the step controller via the serial interface

and

• the CNC mode of the controller: The step controller works independently, without PC coupling of the stored user program (stand alone).

### Ordering information

IT 116 Flash step controller (115V AC, 60 Hz) IT 116 Flash step controller (230V AC, 50 Hz)

Accessories

### Motor lead M23 12-pin socket - SubD 9-pin Pin Part no.: 392755 0200 (2m) Part no.: 392755 0300 (3m) Part no.: 392755 0500 (5m)

Part no.: 381016 0115 \* Part no.: 381016 \*

\* including PAL-PC

Motor lead SubD 9-pin socket - plug 1:1 Part no.: 392780 0081 (0.8m) Part no.: 392780 0151 (1.5m) Part no.: 392780 0201 (2.0m) Part no.: 392780 0301 (3.0m)

# IT116 Flash

### **Features**

- Final output stage 48V DC/4.2A peak for 2-phase step motors
- max. 25,600 microsteps/turn
- Mains voltage: 115V AC/230V AC, 50...60 Hz
- Automatic current sink at 50% phase current at motor speed < 1 rpm
- Motor current/microstep resolution variable with DIP switch
- Integrated 32-bit RISC processor (Embedded controller) with Flash memory for firmware and PAL PC user program
- RS-232 interface (frontal) for coupling with PC/notebook (program download)
- optional: USB interface (frontal) for loading user programs from an USB memory stick (USB on the go)
- Control signals Program start/stop, reset to controller back side
- 4 optically isolated signal inputs (Signal voltage : 24V DC)
- 4 relay outputs (24V DC, 300 mA)
- Motor brake controller (24V DC)
- Remote plug on rear of controller for external EMERGENCY SHUTDOWN (2-channel), external power on • Euro cooling rib casing
- Programming with PAL-PC 2.1
- for Win2000, XP, Vista, 7 • Dimensions W 105  $\times$  H 111  $\times$  D 320 mm

### Scope of supply

- Controller in cassette casing
- Mating plug (I/O, pulse, remote)
- serial interface lead (SubD9 - RJ 45)
- 230V AC mains lead
- PAL-PC software CD
- Operating instructions
- Programming instructions

Subject to technical changes

made by **isel**°

# **Step controllers**

Multiple axis controller



Figure: Front and rear iMC-P step controller

### General

**iMC-P** step controllers **iMC-P** are freely programmable compact controllers with max. 4 final stages for 2-phase step motors.

The controllers integrate all necessary components (interfaces, motion controllers, power supply, final stages, safety circuit incl. door controller, control elements), which are needed to control a machine, in a compact bench housing. The iMC-P1 controller with core module with at least one integrated final stage enables the control of up to 3 additional final stages with clocking/direction module. The signals needed for this are provided through the appropriate external interfaces.

• iMC-P1n: with intelligent core module for control via RS232 The controller also works either in DNC mode (permanently connected with the computer) or in CNC mode (after transfer of the user program as a standalone controller), e. g. via the accompanying PAL-PC software

### Ordering information

2-axis controller iMC-P1-2 3-axis controller iMC-P1-3 4-axis controller iMC-P1-4 USB - RS232 converter Part no.: 372000 0001 Part no.: 381403 0002\* Part no.: 381403 0003\* Part no.: 381403 0004\*

### \* including PAL-PC

### Accessories

Motor lead SubD9 plug - SubD9 socket Part no.: 392780 0151 (1.50 m) Part no.: 392780 0201 (2.00 m) Part no.: 392780 0301 (3.00 m)

Motor lead SubD9 plug - M23 socket Part no.: 392755 0200 (2.00 m) Part no.: 392755 0300 (3.00 m) Part no.: 392755 0400 (4.00 m)

Part no.: 392755 0500 (5.00 m) Part no.: 392755 0600 (6.00 m) Part no.: 392755 0800 (8.00 m) ... other lengths to order.

# **Features**

**iMC-P** 

- 8 signal inputs (24V DC)
- 8 relay outputs (24V DC, 300 mA) max. 2A total current
- 1 relay output (230V AC/6A)
- 1 analogue output (0 10V)
- RS232 programming interface (rear)
- 32-bit RISC processor and memory for user program
- Programming with PAL-PC (DNC and CNC modes), @-format (DNC and CNC modes), ProNC, Remote, Galaad, Labview (DNC mode), various high level languages
- max. 4 final stages (48V/4.2A) for 2-phase step motors (power supply unit 500 W)
- from a step angle of 1.8° up to 25,600 microsteps/turn (1/128 microstep)
- automatic current sink
- motor current adjustable via DIP switch
- additional control signals (start, stop, reset) adaptable
- Safety circuits (emergency shutdown, door circuit controller) via external plugs in higher level safety circuits integrable
- Broadband mains supply: 110 - 250V AC, 50..60 Hz
- Clocking/direction module to order
- Bench casing W 379  $\times$  H 137  $\times$  D260

### Deliverables

- Controller
- Mating plug (I/O, pulse, remote)
- serial interface lead (null modem)
- 230V AC mains lead
- PAL-PC software CD
- Operating and programming instructions

# **Step controllers**

Multiple axis controller





Figure: iMC-S8 step controller as bench version and with 19" housing

### General

The **iMC-S8** step controller is a freely programmable compact controller for linear or circular axes with 2-phase step motors.

The controller integrates all the necessary components (power supply, safety circuit, power electronics, core processor, interfaces, operating elements) that are needed to control individual spindles all the way to entire machines. It has an intelligent core module that is controlled and programmed via a RS232 interface. The core module also converts the commands programmed in the user program into clocking/direction signals for the connected final stages. Depending on the purpose, the **iMC-S8** controller can be used either in CNC or in DNC mode.

In CNC mode, the processor processes the CNC program which was previously produced with PAL-PC and stored in the controller's Flash memory.

In DNC mode, the **iMC-S8** controller is connected permanently with a control computer (PC, laptop) via a serial interface (RS232). Processing is carried out via the isel control software Remote.

### Ordering information

2-axis iMC-S8 step controller, bench housing 2-axis iMC-S8 step controller, 19" housing

3-axis iMC-S8 step controller, bench housing 3-axis iMC-S8 step controller, 19" housing

4-axis iMC-S8 step controller, bench housing 4-axis iMC-S8 step controller, 19" housing

### Part no.: 383320 2002 \* Part no.: 383320 1002 \* Part no.: 383320 2003 \*

Part no.: 383320 1003 \* Part no.: 383320 2004 \* Part no.: 383320 1004 \*

\* including PAL-PC

Controller, mating plug (I/O, pulse, Remote), serial interface lead (null modem), 230V AC mains lead, PAL-PC software CD, operating instructions, programming instructions

Subject to technical changes.

Deliverables

made by **isel**°

**iMC-S8** 

### **Features**

- 32-bit RISC processor with Flash memory for user program
- Final output stages
- Step resolution and motor current adjustable via variable DIP switch - automatic current sink
- Acceleration, start-stop frequency and step output frequency variable
- both hardware limit switches configurable
- Door controller/hood controller
- Control elements in the front of the casing
- external EMERGENCY SHUTDOWN and POWER connection for integration in higher level safety circuits
- Connection for external control signals, such as START, STOP, RESET (only CNC mode)
- 230V connection for milling spindle (100-230V AC)
- 0 .. 10V analogue output for external frequency converter for speed-controlled main spindle
- Programming/Operation
- PAL-PC in CNC mode (in the deliverables)
- Remote (optional: ProNC) in DNC mode
- isel @ format in CNC/DNC modes

### Technical specification

- Broadband mains supply
- 100 250V AC, 50..60Hz
- Processor - Flash memory 128 kB,
- Capacity to store 350 commands - max. step output frequency 40 kHz
- Final stages
- Power supply 48V DC Peak current: 2.8 7.8A
- Step resolution: 400-51200 steps
- Inputs/outputs
- 8 inputs (24V DC)
- 8 outputs (24V DC/300mA, Itot 2A)
- 1 relay output (230V AC, max. 6A)
- 1 analogue output (0 10V)
- RS232 operating/programming interface
- Stop category 1, safety category 2
- Versions: - Bench casing
- W 475  $\times$  H  $\breve{4}$ 10  $\times$  D 187.5 mm - 19" housing
- W 482.5  $\times$  H 410  $\times$  D 175.5 mm

### **Accessories**

Motor lead M23 plug - M23 socket Part no.: 392750 0300 (3m) Part no.: 392750 0500 (5m)

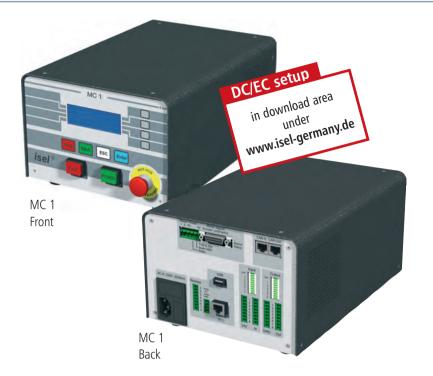
Motor lead M23 plug - SubD9 socket Part no.: 392752 0300 (3m) Part no.: 392752 0500 (5m)

Controller software - Remote Part no.: **Z12-334500** 

Controller and programming software ProNC Part no.: Z11-333500

# Servo controller

Single axis controller



### General

Servo controllers in the MC1 series are freely programmable compact controllers for a linear or rotary unit with servomotor.

The single axis controllers integrate all necessary components (interfaces, motion controller, power supply, drive controller, safety circuit, control elements), which are needed to control a machine, in a compact bench housing. The supplied PAL-PC software can be used for programming.

Two versions are available:

- MC-10: For controlling brush DC servomotors
- MC-20: For controlling brushless EC servomotors

### **Ordering information**

MC1-10 (including PAL-PC) MC1-20 (including PAL-PC) Part no.: 381518 0010 Part no.: 381518 0020

Motor lead Encoder lead

Part no.: 392760 xxxx \* Part no.: 392740 xxxx \*

\* Lead length [mm] available in different lengths. e.g.:  $010\overline{0} = 1.00 \text{ m}/0150 = 1.50 \text{ m}/020\overline{0} = 2.00 \text{ m} \dots 1000 = 10.00 \text{ m}$ 

# MC 1-10/1-20

### **Features**

### MC-10

- for controlling brush servomotors
- Commissioning program "DcSetup"
- For technical specification for the drive controller see "iMD10 drive controller"

### MC-20

- for controlling brushless servomotors
- Analysis of Hall signals
- Commissioning program "AcSetup"
- For technical specification for the drive controller see "iMD20 drive controller"

### Common features

- Max. output power 500 W
- 32-bit high performance RISC
- processor with 256 kB Flash memory • User program in CNC mode for
- up to 650 commands
- Processing of the program in CNC or DNC mode
- Programming with PAL-PC CNC mode), @-format (CNC mode), ProNC, Remote (DNC mode)
- LC display with 4 lines, each with 20 characters (freely programmable)
- additional control signals (Start, Stop) adaptable
- Connection for incremental encoder
- 6(8) signal inputs (24V DC)
- 8 relay outputs (24V DC/700 mA)
- Stop category 0 to EN60204
- Emergency shutdown circuit via plug in higher level safety circuit can be integrated
- Broadband mains supply: 110 - 250V AC, 50..60 Hz
- Bench casing W 204  $\times$  H 149  $\times$  D286

### **Deliverables**

- Controller
- mating plug (I/O, pulse, Remote)
- serial interface lead (SubD9 - RJ 45)
- 230V AC mains lead
- PAL-PC software CD
- Operating instructions
- Programming instructions

# Servo controller

Multiple axis controller



Figure: Front and rear iMC-DC servo controller

### General

CAN controllers in the iMC-DC and iMC-EC series are compact, powerful drive controllers for 2 to 6 DC servomotors at an ideal price/performance ratio. The attractive bench housing integrates all control components which are needed to solve a wide variety of automation tasks. They range from the final stage via the I/O assembly to the safety controller. In addition, a 26 cm (10.2") touch screen TFT display and a keyboard are incorporated, which makes for convenient operation.

A CANopen PCI board is integrated in the control computer as an interface. This acts as the CAN master for the drive controller and the I/O module. In addition, external expansions up to 128 CAN nodes are possible with ease.

The NC controller core allows interpolation of up to 6 axes (linear, circular and helical) and online and lock ahead track processing. When using the ProNC software, individual axes can be controlled as handling axes (in addition to the interpolating axes).

All final stages have automatic jerk limitation and rest state monitoring (up to safety category 3).

### Number of axes Ordering information 2 = 2 axes

3 = 3 axes 4 = 4 axes 5 = 5 axes

6 = 6 axes

Versions

 $1 = iMC-DC^*$  (brush DC servomotors)  $\mathbf{2} = \mathsf{i}\mathsf{MC}-\mathsf{EC}^*$  (brushless EC servomotors)

### **Accessories**

354000X0X0

Motor lead M23 pin - M23 socket Part no.: 392759 0300 (3m) Part no.: 392759 0500 (5m)

Subject to technical changes

made by **isel**"

# **iMC-DC/iMC-EC**

### **Features**

- Drive controller for up to 6 brush or brushless DC servomotors
- NC control via CANopen field bus
- iMD10/iMD20 final output stages - 4-quadrant drive controller - Analysis for incremental encoder
  - Rest state monitoring
  - Over- and undervoltage protection, Overtemperature protection, short-circuit proof
- Door controller/hood controller
- external EMERGENCY SHUTDOWN and POWER connection for integration in higher level safety circuits
- · Connection for external control signals, such as START, STOP, RESET via signal inputs
- Connection for milling spindle (100 -230V AC)
- 0 .. 10V output for external frequency converter for speed-controlled main spindle
- Control elements in the front of the casing
- Industrial control computer running under Windows® with
  - CANopen PCI board
  - Driver software for CNC controller
- Programming/Operation
- Remote (optional: ProNC)

### Technical specification

- Broadband mains supply - 115V AC/230V AC, 50..60 Hz
- Switching power supply 1000W/48V
- iMD10/iMD20 final output stages - Power supply 24 - 80V DC
- Peak current/rated current: 25A/12 A Inputs/outputs
- 16 digital inputs
  - 8 digital outputs
  - 1 analogue output
- Safety controller
- up to safety category 3
- Door circuit controller
- Spindle controller
- Bench casing
- W 630  $\times$  H 230  $\times$  D 400 mm
- Option: without TFT display and keyboard

### Scope of supply

- Controller
- mating plug (I/O, pulse, Remote)
- 230V AC mains lead
- PAL-PC software CD
- Operating and programming instructions

Part no.: 392740 0300 (3m) Part no.: 392740 0500 (5m)

\* including PAL-PC

Encoder lead SubD 15 plug -

SubD15 socket



### **Power unit** Multiple axis controller

# iPU-DC / iPU-EC



Figure: Power unit iPU as bench version and with 19" housing

### General

The iPU power units are powerful drive controllers for up to four linear or circular axes with brush or brushless motors. The compact controller integrates all necessary controller components, which are needed to solve a wide range of automation tasks. These range from iMD10 or iMD20 final output stages through the I/O module to safety control and power electronics.

As its interface for NC control, the **iPU power unit** has a CANopen interface at the back of the housing, which works according to the DS301 bus protocol and DS402. By using the optional CAN PCI board iCC 10 or a iPC series control computer, the controller can control interpolation (linear, circular, helical) of all four axes as well as track processing.

The final output stages (iMD10 or iMD20) also have automatic jerk limitations and rest state monitoring.

The control elements integrated in the front of the housing, such as EMERGENCY SHUTDOWN, START or STOP enable convenient operation.

### **Ordering information** 3 5 3 0 0 0 X 0 X X

### Number of axes 2 = 2 axes 3 = 3 axes

4 = 4 axes

Versions

### **Drive controllers**

1 = 19'' housing

### 1 = iMD 10 (brush DC servomotors)

 $\mathbf{2} = \text{Bench housing}$   $\mathbf{2} = \text{iMD 20}$  (brushless EC servomotors) \* in preparation, available to order

### Accessories

Motor lead M23 plug - M23 socket

Encoder lead SubD15 plug - SubD15 socket

CAN PCI board iCC 10 (single channel) CAN PCI board iCC 20 (2 channels) Controller software - Remote ProNC control software

### Part no.: 392759 0300 (3 m) Part no.: 392759 0500 (5 m) Part no.: 392740 0300 (3 m) Part no.: 392740 0500 (5 m) Part no.: 320310 Part no.: 320311 Part no.: **Z12-334500** Part no.: Z11-333500

### **Features**

- Drive controller for up to four brush or brushless DC servomotors
- NC control via CANopen field bus
- iMD10/iMD20 final output stages - 4-guadrant drive controller
  - Analysis for incremental encoder
  - Rest state monitoring
  - Over- and undervoltage protection, Overtemperature protection, short-circuit proof
- Door controller/hood controller
- Connection for external control signals, such as EMERGENCY SHUTDOWN, START, STOP FOR Integration in higher level safety circuits
- Connection for milling spindle (100 -230V AC)
- 0 .. 10V output for external frequency converter for governed main spindle
- Control elements in the front of the casing (optionally, installed in the rear)
- two alternative casings
- Programming/Operation - Remote (optional: ProNC)

### Technical specification

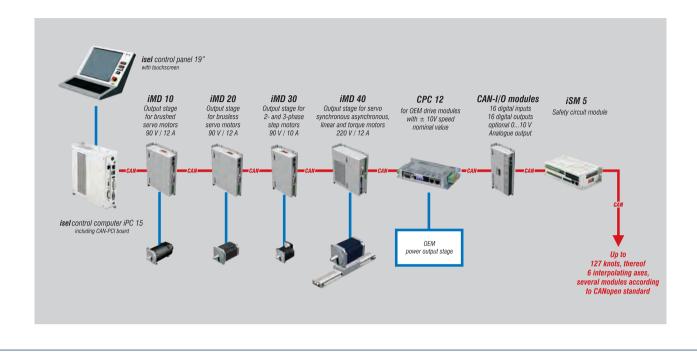
- Broadband mains supply - 115V AC/230V AC, 50..60 Hz
- Switching power supply unit 1000 W/48 V
- iMD10/iMD20 final output stages - Power supply 24 - 80V DC
  - Peak current/rated current: 25A/12 A
- Inputs/outputs
  - 4 digital inputs (24V DC/8mA)
  - 8 digital outputs (24V DC/350mA)
  - 1 relay output (230V AC, max. 6A)
  - 1 analogue output (0 10V)
- Safety controller
  - up to safety category 3
  - Door circuit controller
  - Spindle controller
- RJ 45 CANopen interface
- Versions:
- Bench housing W 475  $\times$  H 410  $\times$  D 187.5 mm
- 19" housina W 482.5 imes H 410 imes D 175.5 mm

### Scope of supply

- Controller
- mating plug (I/O, pulse, Remote)
- CAN bus lead (RJ45, patch lead)
- 230V AC mains lead
- Operating instructions

# CAN-CNC controller

Example of a topology with the isel-CAN-CNC controller



With consequent use of the CiA's (CAN in automation) CANopen standards, isel Germany delivers a high quality PC-based CAN-CNC controller for intelligent positioning/drive units and I/O modules.

The **CAN-CNC controller** supports interpolation operation (linear, circular and helical) of up to six positioning drives per machine and up to 127 handling axes and CAN modules.

The high time demands of a CNC controller are guaranteed by a WDM driver developed by isel. An additional real time operating system for Windows will be unnecessary. This guarantees compatibility with future Windows versions (Win7 in preparation)

The CAN controller is a pure software solution for PCs with Windows 2000/XP/VISTA. The CANopen PCI boards iCC 10/20 also act as an interface.

Owing to the features provided, the CAN-CNC controller is equally suited for all machining tasks, such as milling, engraving, drilling, turning, water jet and laser cutting, as well as for applications in automation systems.

For this purpose, **ProNC** provides a universal programming environment.

### **Features**

- Machine control to the CANopen standard as a pure software solution for PCs with Windows 2000/XP/VISTA
- CiA-Standard, DS 301, DSP 401, DSP 402
- Supports up to six positioning axes and 127 handling axes and CAN modules.
- Look ahead track processing with a freely definable number of movement elements, which the controller processes to a forecast.
- Jerk limitation for elimination of mechanical vibrations
- Upstream speed control for highly dynamic and lag error-free machining
- Software tools for setting and optimising motor final stages/positioning modules
- Interfaces for PC:
  - CANopen PCI board iCC 10 (single channel) CAN bus 1
  - CANopen PCI board iCC 20 (two channels CAN buses 1 and 2